8GP60-090 premium

Technical data



8GP60-090hh003klmm	8GP60-090hh004klmm	8GP60-090hh005klmm	8GP60-090hh008klmm	8GP60-090hh010klmm	8GP60-090hh012klmm	8GP60-090hh015klmm	8GP60-090hh016klmm	8GP60-090hh020klmm	8GP60-090hh025klmm	8GP60-090hh032klmm	8GP60-090hh040klmm	8GP60-090hh064klmm	8GP60-090hh100klmm
--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------	--------------------

Gearbox															
Number of gear stages	1	1	1	1	1	2	2	2	2	2	2	2	2	2	
Gear ratio i	3	4	5	8	10	12	15	16	20	25	32	40	64	100	
Nominal output torque T _{2N} [Nm]	100	140	140	80	60	110	110	150	150	140	150	140	80	60	
Max. output torque T _{2max} [Nm]	160	224	224	128	96	176	176	240	240	224	240	224	128	96	
E-stop torque T _{2stop} [Nm]	210	280	280	200	200	220	220	300	300	300	300	300	200	200	
Idle torque [Nm] at 20°C and 3000 rpm	1.15	1	0.75	0.5	0.4	0.7	0.55	0.7	0.5	0.5	0.35	0.35	0.35	0.3	
Max. average drive speed $\rm n_{1N50\%}$ [rpm] at 50% $\rm T_{2N}$ and S1	1950	2100	2500	3950	4000	3400	4000	3550	4000	4000	4000	4000	4000	4000	
Max. average drive speed $n_{1N100\%}$ [rpm] at $100\%\ T_{2N}$ and S1	1550	1600	1900	3350	4000	2750	3300	2850	3400	3850	4000	4000	4000	4000	
Max. drive speed n _{1max} [rpm] 10000									00						
Max. backlash J _t [arcmin]	3	3	3	3	3	5	5	5	5	5	5	5	5	5	
Reduced backlash J _t [arcmin] less than								1							
Torsional rigidity C ₁₂₁ [Nm/arcmin]	9	9	9	9	9	10	10	10	10	10	10	10	10	10	
Tilting rigidity C _{2K} [Nm/arcmin])							
Max. breakdown torque M _{2Kmax} [Nm])							
Max. radial force Fr _{max} [N] for 30,000 h							48	00							
Max. radial force Fr _{max} [N] for 20,000 h							55	00							
Max. axial force Fa _{max} [N] for 30,000 h							57	00							
Max. axial force Fa _{max} [N] for 20,000 h							64	00							
Operating noise L _{PA} [dB(A)]							6	0							
Efficiency at full load η [%]	98	98	98	98	98	95	95	95	95	95	95	95	95	95	
Min. operating temperature B _{Tempmin} [°C]							-2	25							
Max. operating temperature B _{Tempmax} [°C]							9	0							
Mounting orientation							Α	ny							
Protection							IP	65							
Weight m [kg]	3.3	3.3	3.3	3.3	3.3	4.2	4.2	4.2	4.2	4.2	4.2	4.2	4.2	4.2	
Moment of inertia J₁ [kgcm²]	1.01	0.78	0.68	0.59	0.57	1.02	0.95	0.89	0.82	0.76	0.77	0.7	0.63	0.59	

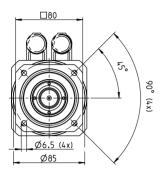
NOTE – Output torque / Max. output torque: This refers to an output shaft speed of $n_2 = 100$ rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and $T = 30^{\circ}$ C, depending on the diameter of the motor shaft. The maximum output torque is only permissible for 30,000 revolutions!

NOTE – E-stop torque: Approved for 1000x

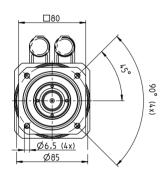
NOTE – Axial / radial force: With reference to the middle of the output shaft; the entries refer to an output shaft speed of $n_2 = 100$ rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $K_A = 1$ as well as S1 operating mode for electrical machines and T = 100 rpm and application factor $T_A = 100$ rpm and $T_A = 100$ rpm a

NOTE – Running noise: Noise level at a distance of 1 m; at an output speed of $n_1 = 3000$ rpm without a load; i = 5 **NOTE – Operating temperature:** With reference to the middle of the housing surface **NOTE – Weight:** Planetary gearbox including universal flange (specific weight upon request)

1-stage gear

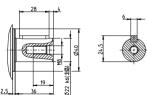


2-stage gear

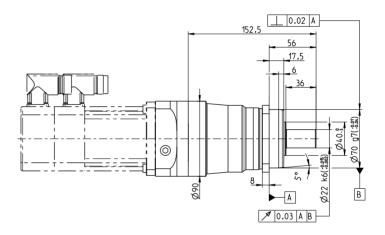


Alternative drive shaft options

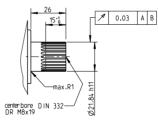




120.5 56 177.5 6 36 70.03 A B



Spline shaft according to DIN 5480 - W 22 x 1.25 x 30 x 16 x 6 m $\,$



Adapter flange - Overview of dimensions

The flange length L completes the diagram for determining the gearbox length.

8GP60-090	8LSA3	8LSA/C4	8LVA2	8LVA3	8JSA3	8JSA4	8JSA5	8LSN4	80MPH
Flange length L [mm]	38.8	48.8	38.8	48.8	38.8	48.8	58.9	48.8	38.8
Flange diameter Q [mm]	90	115	90	90	90	90	115	115	90