8CVI088S1HCS0.00-1

1 Order data



Table 1: 8CVI088S1HCS0.00-1 - Order data

Model number	Short description
8CCH0010.11150-1	Hybrid cable for connecting 8EI to 8CVI or 8DI, length 10 m, 2x
	$2x 0.34 \text{ mm}^2 + 4x 0.75 \text{ mm}^2 + 5x 2.5 \text{ mm}^2$, $1x 15$ -pin female
	TYCO connector, 1x RJ45 connector, integrated shield fixing,
000110045 44450 4	can be used in cable drag chains
8CCH0015.11150-1	Hybrid cable for connecting 8EI to 8CVI or 8DI, length 15 m, 2x 2x 0.34 mm ² + 4x 0.75 mm ² + 5x 2.5 mm ² , 1x 15-pin female
	TYCO connector, 1x RJ45 connector, integrated shield fixing,
	can be used in cable drag chains
8CCH0020.11150-1	Hybrid cable for connecting 8EI to 8CVI or 8DI, length 20 m, 2x
0CC110020.11130-1	2x 0.34 mm ² + 4x 0.75 mm ² + 5x 2.5 mm ² , 1x 15-pin female
	TYCO connector, 1x RJ45 connector, integrated shield fixing,
	can be used in cable drag chains
8CCH0025.11150-1	Hybrid cable for connecting 8EI to 8CVI or 8DI, length 25 m, 2x
	2x 0.34 mm ² + 4x 0.75 mm ² + 5x 2.5 mm ² , 1x 15-pin female
	TYCO connector, 1x RJ45 connector, integrated shield fixing,
	can be used in cable drag chains
	SinCos cables
8CCS0003.11110-0	ACOPOSremote SinCos cable, length 3 m, 10x 0.14 mm ² +
	2x 0.5 mm², 12-pin female springtec connector, 15-pin male
	springtec connector, can be used in cable drag chains
8CCS0005.11110-0	ACOPOSremote SinCos cable, length 5 m, 10x 0.14 mm ² +
	2x 0.5 mm², 12-pin female springtec connector, 15-pin male
	springtec connector, can be used in cable drag chains
8CCS0010.11110-0	ACOPOSremote SinCos cable, length 10 m, 10x 0.14 mm ² +
	2x 0.5 mm², 12-pin female springtec connector, 15-pin male
20000045 44440 0	springtec connector, can be used in cable drag chains
8CCS0015.11110-0	ACOPOSremote SinCos cable, length 15 m, 10x 0.14 mm² +
	2x 0.5 mm², 12-pin female springtec connector, 15-pin male
	springtec connector, can be used in cable drag chains
V074 001400	Threaded caps
X67AC0M08	X67 M8 threaded caps, 50 pcs.
X67AC0M12	X67 M12 threaded caps, 50 pcs.

Table 1: 8CVI088S1HCS0.00-1 - Order data

2 Technical data

Model number	8CVI088S1HCS0.00-1		
General information			
Module type	ACOPOSremote module		
B&R ID code	0xDDA6		
Current-carrying capacity of 15-pin TYCO connector			
Power contacts	Max. 20 A at 40°C		
Cooling and mounting type	Cold plate mounting		
Certifications			
CE	Yes		
UL	cULus E225616 Power conversion equipment		
Functional safety ¹⁾	Yes		
DC bus connection			
Voltage			
Nominal	750 VDC		
Continuous power consumption 2)	In preparation		
Power dissipation depending on switching frequency			
Switching frequency 5 kHz	[0.16 * I _M ² + 5.6 * I _M + 55 + (P _{out} /750) ² * 0.25] W		
Switching frequency 10 kHz	[0.49 * I _M ² + 4.7 * I _M + 95 + (P _{out} /750) ² * 0.25] W		
Switching frequency 20 kHz	$[0.87 * I_{M}^{2} + 10 * I_{M} + 200 + (P_{out}/750)^{2} * 0.25] W$		
DC bus capacitance	35 μF		
Variant	15-pin male TYCO connector 3)		
Line length			
Maximum	30 m		
24 VDC power supply			
Input voltage	24 VDC +20% / -25%		
Input capacitance	In preparation		
Max. power consumption	10 W + P _{24 V out} + P _{Holding brake} + P _{Trigger} ⁴⁾		
Variant	15-pin male TYCO connector 3)		
Line length			
Maximum	30 m		
24 VDC output			
Quantity	1		
Output voltage	Depends on the 24 VDC power supply		
Continuous current	Max. 8 A (max. 4 A per pin)		
Fuse protection Electronic (per pin)			

Table 2: 8CVI088S1HCS0.00-1 - Technical data

Model number	8CVI088S1HCS0.00-1	
Variant	00410000111000.00-1	
24 VDC, COM	M8 connector	
Motor connection	1110 00-111100001	
Quantity	1	
Continuous power per motor connection 2)	4 kW	
Continuous current per motor connection 2)	8.8 A _{eff}	
Reduction of continuous current depending on		
switching frequency 5)		
Switching frequency 5 kHz	No reduction 6)	
Switching frequency 10 kHz	No reduction	
Switching frequency 20 kHz	No reduction	
Reduction of continuous current depending on installation elevation		
Starting at 500 m above sea level	0.88 A per 1,000 m	
Peak current	24.5 A _{eff}	
Nominal switching frequency	5 kHz	
Possible switching frequencies 7)	5 / 10 / 20 kHz	
Electrical stress of connected motor per IEC TS 60034-25 8)	Limit value curve A	
Protective measures		
Overload protection	Yes	
Short circuit and ground fault protection	Yes	
Max. output frequency	598 Hz ⁹⁾	
Variant		
U, V, W, PE	8-pin speedtec connector, size 1	
Shield connection	Yes (via connector housing)	
Max. motor line length depending on switching fre-		
quency		
Switching frequency 5 kHz	10 m	
Switching frequency 10 kHz	5 m	
Switching frequency 20 kHz	5 m	
Motor holding brake connection	4	
Quantity Output voltage 10)	1 24 VDC +5.8% / -0%	
Continuous current	1.1 A	
Max. internal resistance	In preparation	
Extinction potential	Approx. 30 V	
Max. extinction energy per switching operation	1.5 Ws	
Max. switching frequency	0.5 Hz	
Protective measures	0.0112	
Overload and short-circuit protection	Yes	
Open circuit monitoring	Yes	
Undervoltage monitoring	Yes	
Response threshold for open circuit monitoring	Approx. 0.25 A	
Response threshold for undervoltage monitoring	24 VDC +0% / -4%	
Fieldbus		
Туре	POWERLINK (V1/V2) 100BASE-T (ANSI/IEE 802.3)	
Variant	Internal 3-port hub, 2x male 15-pin TYCO connector, 1x M12 connector	
Line length	Max. 100 m between two stations (segment length) 11)	
Transfer rate	100 Mbit/s	
Encoder inputs		
Quantity	1	
Туре	SinCos	
Module-side connection	15-pin female springtec connector	
Status indicators	UP/DN LEDs	
Electrical isolation		
Encoder - ACOPOSremote	No	
Encoder monitoring	Yes	
Max. encoder cable length	10 m	
Encoder power supply		
Output voltage	5 V ±5%	
Load capacity	300 mA ¹²⁾	
Sense lines	2, compensation of max. 2 x 0.7 V	
Protective measures		
Overload-proof Yes		
Short-circuit proof	Yes	

Table 2: 8CVI088S1HCS0.00-1 - Technical data

8CVI088S1HCS0.00-1

Model number	8CVI088S1HCS0.00-1	
Sine/Cosine inputs	00410003111030.00-1	
Signal transmission	Differential signals, symmetrical	
-	• • •	
Signal frequency (-3 dB)	DC up to 300 kHz	
Signal frequency (-5 dB)	DC up to 400 kHz	
Differential voltage	0.5 to 1.25 V _{ss}	
Common-mode voltage	Max. ±7 V	
Terminating resistor	120 Ω	
ADC resolution	12-bit	
Reference input		
Signal transmission	Differential signal, symmetrical	
Differential voltage for low	≤-0.2 V	
Differential voltage for high	≥0.2 V	
Common-mode voltage	Max. ±7 V	
Terminating resistor	120 Ω	
Position		
Resolution @ 1 V _{SS} ¹³⁾	Number of encoder lines * 5700	
Accuracy 14)	-	
Noise 14)		
	-	
Limit switch inputs 15)		
Quantity	2	
Circuit	Source	
Input resistance	1470 Ω	
Electrical isolation		
Input - ACOPOSremote	No	
Input - Input	No	
Input voltage		
Minimum	-12 V	
Nominal	5 V	
Maximum	20 V	
Switching threshold		
Low	<0.8 V	
High	>2 V	
Switching delay	Max. 100 μs	
Enable inputs	Ιπαλ. 100 μο	
Quantity	2	
Circuit	Sink	
Electrical isolation	Ollik	
Input - Inverter module	Yes	
Input - Inverter module	Yes	
	tes	
Input voltage	041/00	
Nominal	24 VDC	
Maximum	30 VDC	
Input current at nominal voltage	Approx. 30 mA	
Switching threshold		
Low	<5 V	
High	>15 V	
Switching delay at nominal input voltage		
Enable 1 → 0, PWM off	Max. 20.5 ms	
Enable 0 → 1, ready for PWM	Max. 100 μs	
Modulation compared to ground potential	Max. ±38 V	
OSSD signal connections ¹⁶⁾	Permissible	
	Max. test pulse length: 500 μs	
Variant	15-pin male TYCO connector 3)	
Trigger inputs		
Quantity	2	
Circuit	Sink	
Electrical isolation	,	
Input - Inverter module	No	
Input - Inverter module	No	
· · · · · · · · · · · · · · · · · · ·	INU	
Input voltage	241/00	
Nominal	24 VDC	
Maximum	30 VDC	
Switching threshold		
Low	<5 V	
High	>15 V	
Input current at nominal voltage	In preparation	
Switching delay		
Rising edge	In preparation	
Falling edge	In preparation	
	i i	
Modulation compared to ground potential	In preparation	
Modulation compared to ground potential Max. line length	In preparation 30 m	
Modulation compared to ground potential Max. line length Variant	In preparation 30 m M8 connector	

Table 2: 8CVI088S1HCS0.00-1 - Technical data

Model number	8CVI088S1HCS0.00-1		
Sensor/Actuator power supply			
Voltage	24 VDC		
Summation current	Max. 250 mA ¹⁷⁾		
Support			
Software			
ACP10	V2.35.1 and higher		
Electrical properties	·		
Discharge capacitance	0.1 μF		
Operating conditions	·		
Permissible mounting orientations			
Hanging vertically	Yes		
Horizontal, face up	Yes		
Standing horizontally	Yes		
Installation elevation above sea level			
Nominal	0 to 500 m		
Maximum 18)	4000 m		
Pollution degree per EN 61800-5-1	2 (non-conductive pollution)		
Overvoltage category per EN 61800-5-1			
Degree of protection per EN 60529	IP65 19)		
Ambient conditions			
Temperature			
Operation			
Nominal	5 to 40°C ²⁰⁾		
Maximum	60°C		
Storage	-25 to 55°C		
Transport	-25 to 70°C		
Relative humidity			
Operation	5 to 85%, non-condensing		
Storage	5 to 95%, non-condensing		
Transport	Max. 95% at 40°C		
Mechanical properties			
Dimensions ²¹⁾			
Width	137 mm		
Height	287.2 mm		
Depth	131 mm		
Weight	4.8 kg		

Table 2: 8CVI088S1HCS0.00-1 - Technical data

- 1) Achievable safety classifications (safety integrity level, safety category, performance level) are documented in the user's manual (section "Safety technology").
- 2) Valid under the following conditions: 750 VDC DC bus voltage, 5 kHz switching frequency, 40°C ambient temperature, installation elevation <500 m above sea level, no derating due to cooling type.
- 3) It is important to note that the 15-pin male TYCO connector is designed for max. 20 mating cycles.
- 4) The power consumption $P_{24 \text{ V Out}}$ corresponds to the portion of the power that is output on the X31 connector on the module.
- 5) Valid under the following conditions: 750 VDC DC bus voltage. The temperature specifications refer to the ambient temperature.
- 6) Value for the nominal switching frequency.
- 7) B&R recommends operating the module at its nominal switching frequency. Operating the module at a higher switching frequency for application-specific reasons reduces the continuous current and increases the CPU utilization.
- 8) If necessary, the stress of the motor isolation system can be reduced by an additional externally wired dv/dt choke. For example, the RWK 305 three-phase du/dt choke from Schaffner (www.schaffner.com) can be used. Important: Even when using a dv/dt choke, it is necessary to ensure that an EMC-compatible, low inductance shield connection is used!
- 9) The module's electrical output frequency (SCTRL_SPEED_ACT * MOTOR_POLEPAIRS) is monitored to protect against dual use in accordance with Council Regulation (EC) 428/2009 | 3A225. If the electrical output frequency of the module exceeds the limit value of 598 Hz uninterrupted for more than 0.5 s, then the current movement is aborted and error 6060 is output ("Power unit: Limit speed exceeded").
- 10) During configuration, it is necessary to check if the minimum voltage can be maintained on the holding brake with the intended wiring. For the operating voltage range of the holding brake, see the user documentation for the motor being used.
- 11) Limited to 30 m when using hybrid cables.
- 12) An additional reserve of 12 mA exists for terminating resistors and limit switch inputs.
- 13) This value does not correspond to the encoder resolution that must be configured in Automation Studio (16384 * number of encoder lines).
- 14) Limited by the encoder in practice.
- 15) The measurement system offered by Heidenhain with limit switch outputs LIDA 47x, LIDA 48x and LIF4x1 was tested for compatibility. In practice, the cable length is limited by the encoder.
- 16) OSSD (output signal switching device) signals are used to monitor signal lines for short circuits and cross faults.
- 17) The summation current corresponds to the current that is output on the X23A and X24A connectors on the module.
- 18) Continuous operation at an installation elevation of 500 m to 4,000 m above sea level is possible taking the specified reduction of continuous current into account. Requirements that go beyond this must be arranged with B&R.
- 19) The specified degree of protection is only met if all connectors on the module that are not being used are closed with suitable threaded caps or slot covers! Suitable threaded caps or slot covers are available as optional accessories (X67AC0M08, X67AC0M12, 8CXC000.0000-00). The module is delivered with IP20 protection.
- The temperature of the module's mounting surface is not permitted to exceed 60°C.
- 21) The dimensions refer to the actual device dimensions. Make sure to leave additional space above and below the devices for mounting and connections.

3 Status indicators

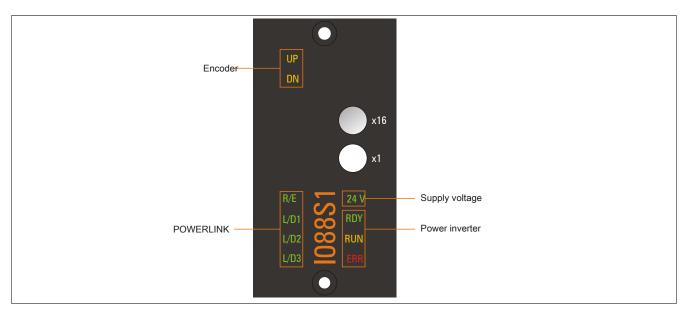


Figure 1: Overview of indicator groups

3.1 LED status indicators

Status indicator group	Label	Color	Function	Description
POWERLINK	R/E	Green/Red	Ready/Error	see Tab. 4 "POWERLINK - LED status indica-
	L/D1	Green	Link/Data activity on port 1	tors" on page 7
	L/D2	Green	Link/Data activity on port 2	
	L/D3	Green	Link/Data activity on port 3	
Power inverter	RDY	Green	Ready	see Tab. 5 "RDY, RUN, ERR - LED status indi-
	RUN	Orange	Run	cators" on page 7
	ERR	Red	Error	
Power supply	24 V	Green	24 V OK	24 VDC module voltage supply is within the tol-
				erance range.
Encoder	UP	Orange	Encoder direction of rotation +	Indicates that the position of the connected encoder is changing in the positive direction. The faster the encoder position changes, the brighter the LED is lit.
	DN	Orange	Encoder direction of rotation -	Indicates that the position of the connected encoder is changing in the negative direction. The faster the encoder position changes, the brighter the LED is lit.

Table 3: 8CVI inverter modules - LED status indicators

3.2 POWERLINK - LED status indicators

Label	Color	Function	Description	
R/E	Green/Red	Ready/Error	LED off	The module is not receiving power or initialization of the network interface has failed.
			Solid red	The POWERLINK node number of the module is 0.
			Blinking red/green	The client is in an error state (drops out of cyclic operation).
			Blinking green (1x)	The client detects a valid POWERLINK frame on the network.
			Blinking green (2x)	Cyclic operation on the network is taking place, but the client itself is not yet a participant.
			Blinking green (3x)	Cyclic operation of the client is in preparation.
			Solid green	The client is participating in cyclic operation.
			Flickering green	The client is not participating in cyclic operation and also does not detect any other stations on the network participating in cyclic operation.
L/D1	Green	Link/Data activity on port 1	Solid green	A physical connection has been established to another station on the network.
L/D2	Green	Link/Data activity on port 2	Solid green	A physical connection has been established to another station on the network.
L/D3	Green	Link/Data activity on port 3	Solid green	A physical connection has been established to another station on the network.

Table 4: POWERLINK - LED status indicators

3.3 RDY, RUN, ERR - LED status indicators

Label	Color	Function	Description	Description		
RDY	Green	Ready	Solid green	The module is operational and the power stage can be enabled (operating system present and booted, no permanent or temporary errors).		
			Blinking green 1)	The module is not ready for operation.		
				Examples:		
				No signal on one or both enable inputs		
				 DC bus voltage outside the tolerance range 		
				 Overtemperature on the motor (temperature sensor) 		
				Motor feedback not connected or defective		
				Motor temperature sensor not connected or defective		
				Overtemperature on the module (IGBT junction, heat sink, etc.)		
				Disturbance on network		
RUN	Orange	Run	Solid orange	The module's power stage is enabled.		
ERR	Red	Error	Solid red 1)	There is a permanent error on the module.		
				Examples:		
				Permanent overcurrent		
				Invalid data in EPROM		

Table 5: RDY, RUN, ERR - LED status indicators

4 Pinouts

Danger!

Before performing service work, disconnect the power supply and wait 5 minutes to ensure that the DC bus of the drive system has discharged. Observe regulations!

Warning!

Drive systems can carry high levels of electrical voltage. Never connect or disconnect the connector when voltage is present!

Information:

To satisfy UL/CSA requirements, components of B&R drive systems are only permitted to be wired with copper wires with a permitted wire temperature of at least 75°C.

¹⁾ Firmware V2.130 and later.

4.1 Overview

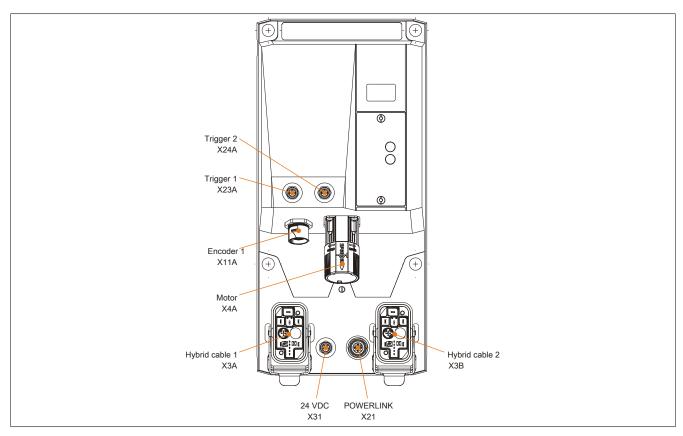


Figure 2: Pinout overview

4.2 X4A (motor connection)

Figure	Pin	Name	Function
	1	U	Motor connection U
DH3	2	PE	Protective ground conductor
(6 0 1 0 3 N	3	W	Motor connection W
150000000000000000000000000000000000000	4	V	Motor connection V
	Α	T+	Temperature +
(BO) OY	В	T-	Temperature -
AIT	С	B+	Brake +
	D	B-	Brake -

Table 6: X4A connector - Pinout

4.3 X11A (SinCos encoder connection)

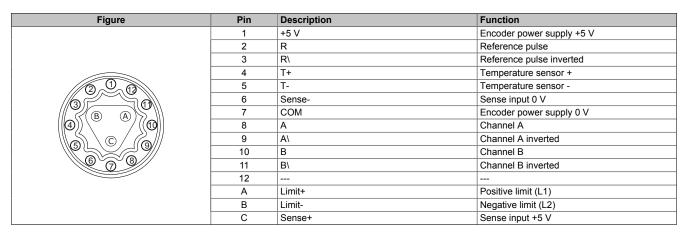


Table 7: X11A SinCos connector - Pinout

4.4 X21 (POWERLINK)

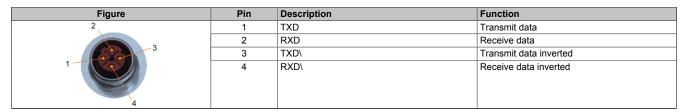


Table 8: Connector X21x/X22x - Pinout

4.5 X23A, X24A (trigger)

Figure	Pin	Description	Function
4	1	+24 V	Sensor/actuator power supply 24 VDC 1)
	3	GND	GND
3	4	Trigger	Trigger input

Table 9: X23A, X24A connector - Pinout

1) Sensors/Actuators are not permitted to be supplied externally.

4.6 X31 (24 VDC routing)

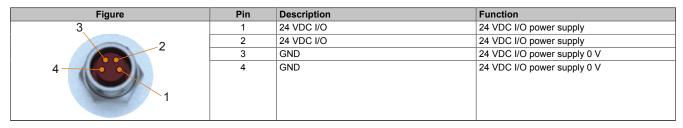


Table 10: Connector X31x - Pinout