# 8EAC0152.001-1

#### **1** General information

Analog multi-encoder plug-in module 8EAC0152.001-1 can be used in the slot on an ACOPOS P3 8EI servo drive. The module contains an analog multi-encoder interface for evaluating analog encoders.

The plug-in module evaluates encoders that are built into B&R servo motors or used to evaluate external axes.

The encoder input signals are monitored. This makes it possible to detect open circuits, short circuits and failures of the encoder power supply (reference signal).

When switched on, the plug-in module is automatically identified by the operating system on the ACOPOS P3 8EI servo drive.

- SinCos
- EnDat 2.1, serial with evaluation of sinusoidal output signals
- HIPERFACE
- · SSI SinCos, serial with evaluation of sinusoidal output signals

#### Information:

The encoder type for the multi-encoder interface is not predefined from the factory. Before commissioning, configure the encoder type in Automation Studio for each multi-encoder interface!

### **Caution!**

An incorrect configuration can result in irreparable damage to the connected encoder!

	SinCos	EnDat 2.1	SSI SinCos	HIPERFACE		
Encoder power supply		5.2 V ±0.1 V		11.45 V ±0.1 V		
Compensation <sup>1)</sup>		Max. 2x 0.7 V				
Terminating resistors		120 Ω				
Signal frequency		DC up to 400 kHz				
Transfer rate		781.25 kbit/s	100 to 400 kbit/s	9600 bit/s		
Support <sup>2)</sup>	ACOP	ACOPOS operating system 5.00.0 and higher				

Table 1: Overview of encoder types

1) Compensation is implemented by configuring the cable resistance in Automation Studio.

2) Operating system version from which a certain encoder type is supported.

### 2 Order data

Model number	Short description	Figure
	Plug-in modules	
8EAC0152.001-1	ACOPOS P3 plug-in module, analog multi-encoder interface	
	Optional accessories	
	Adapter cables	
8ECG00X4.3151D-0	ACOPOS P3 adapter cable, length 0.4 m, for analog multi-en- coder interfaces and incremental encoder interfaces, 5x 2x 0.14 mm <sup>2</sup> , 10-pin male IX connector to 15-pin female DSUB	XIM BEACIEZ 001-1

#### Table 2: 8EAC0152.001-1 - Order data

### **3 Technical data**

8EAC0152.001-1   ACOPOS P3 plug-in module   0xEFDF   Slot 1   12 W   Yes   CULus E225616   Power conversion equipment   Not relevant
OxEFDF Slot 1 12 W Yes Yes cULus E225616 Power conversion equipment
OxEFDF Slot 1 12 W Yes Yes cULus E225616 Power conversion equipment
Slot 1 12 W Yes Yes cULus E225616 Power conversion equipment
12 W Yes Yes cULus E225616 Power conversion equipment
Yes Yes cULus E225616 Power conversion equipment
Yes cULus E225616 Power conversion equipment
Yes cULus E225616 Power conversion equipment
cULus E225616 Power conversion equipment
Power conversion equipment
Not relevant
10-pin male connector
None
75 m
Differential signals, symmetrical <sup>2)</sup>
Depends on the configured encoder type
120 Ω
12-bit
Configurable Typ. 11.45 V ±0.1 V / 5.2 V ±0.1 V
Max. 300 mA for 5.2 V Max. 200 mA for 11.45 V <sup>3)</sup>
None <sup>4</sup>
Yes
Yes
163
Differential signal, symmetrical
≤-0.2 V
≥+0.2 V
120 Ω
2 <sup>14</sup> increments * number of encoder lines
RS485
Depends on the configured encoder type
5.1.0 and higher
5.00.0 and higher
5 to 40°C
55°C
-25 to 55°C
-25 to 70°C
5 to 85%
5 to 95%
Max. 95% at 40°C
82 mm
24 mm
103 mm
64 g

#### Table 3: 8EAC0152.001-1 - Technical data

Achievable safety classifications (safety integrity level, safety category, performance level) are documented in the user's manual (section "Safety technology").

HIPERFACE encoder type: Asymmetrical

1) 2) 3) 4) Up to revision C0, the load capacity is reduced from 200 mA to 100 mA at an output voltage of 11.45 V and ambient temperatures starting at 40°C. Possible to compensate for encoder voltage drop by configuring cable resistance (max. 2x 0.7 V at 5 V output voltage)

#### 4 Wiring

#### 4.1 Pinout

#### Information:

Plug-in module 8EAC is not capable of hot plugging. An 8EAC plug-in module is only permitted to be connected to or disconnected from an ACOPOS P3 8EI servo drive when power to the servo drive is switched off.

Figure	Connector X41M	Pin	Name	Function depending on configured encoder type			
				SinCos	EnDat 2.1	SSI SinCos	HIPERFACE
	AME - 1	1	B\	Channel B inverted	REF cosine		
		2	В	Channel B			Cosine
		3	GND	Encoder power supply 0 V			
		4	A\	Channel A inverted	A inverted		REF sine
AME		5	A	Channel A			Sine
AC0152.001-1		6	R	Reference pulse	Data +	ata +	
	w£J.	7	R\	Reference pulse in- verted	Data -		
	<u>∞£</u> 5 <u></u>	8	U+	Encoder power supply 5 V		Encoder power sup- ply 12 V	
	9 2 2 2 7 7 7 7	9	T-	Temperature sensor	Clock -		Temperature sensor
8EAC		10	T+	Temperature sensor +	Clock +		Temperature sensor +

Table 4: Analog multi-encoder interface 8EAC0152.001-1 - Pinout

## Danger!

The connections for the encoders are isolated circuits. These connections are therefore only permitted to be connected to devices or components that have sufficient isolation per IEC 60364-4-41 or EN 61800-5-1.