

# 8GA45-121

## Technical data



8GA45-121hh003klmm

8GA45-121hh004klmm

8GA45-121hh005klmm

8GA45-121hh008klmm

8GA45-121hh010klmm

8GA45-121hh009klmm

8GA45-121hh012klmm

8GA45-121hh015klmm

8GA45-121hh016klmm

8GA45-121hh020klmm

8GA45-121hh025klmm

8GA45-121hh032klmm

8GA45-121hh040klmm

8GA45-121hh064klmm

8GA45-121hh100klmm

### Gearboxes

Number of stages					1					2									
Ratio i	3	4	5	8	10	9	12	15	16	20	25	32	40	64	100				
Nominal output torque T <sub>2N</sub> [Nm] <sup>1)</sup>	80	105	130	120	95	210	260	230	260		230	260	230	120	95				
Max. output torque T <sub>2max</sub> [Nm] <sup>1)</sup>	128	168	208	192	152	336	416	368	416		368	416	368	192	152				
Emergency stop torque T <sub>2estop</sub> [Nm] <sup>2)</sup>	160	210	260	240	190	420	520	460	520		460	520	460	240	190				
No load running torque at 20°C and 3,000 [min <sup>-1</sup> ] [Nm]	0.8	0.7		0.6						0.5									
Max. average input speed at 50% T <sub>2N</sub> and S1 n <sub>1N50%</sub> [min <sup>-1</sup> ]	3500					3450	3500												
Max. average input speed at 100% T <sub>2N</sub> and S1 n <sub>1N100%</sub> [min <sup>-1</sup> ]	2200	2150		3300		2050	2150	2800	2650	3050	3500								
Max. input speed n <sub>1max</sub> [min <sup>-1</sup> ]	6500																		
Max. backlash j <sub>lt</sub> [arcmin]	<12					<16													
Reduced backlash j <sub>lt</sub> [arcmin]									-										
Torsional rigidity C <sub>t21</sub> [Nm/arcmin]	10					13													
Tilting rigidity C <sub>2K</sub> [Nm/arcmin]									-										
Max. tilting moment M <sub>2KMax</sub> [Nm]									-										
Max. radial force for 30,000 h Fr <sub>max</sub> [N] <sup>3)</sup>									2400										
Max. radial force for 20,000 h Fr <sub>max</sub> [N] <sup>3)</sup>									2950										
Max. axial force for 30,000 h Fa <sub>max</sub> [N] <sup>3)</sup>									2100										
Max. axial force for 20,000 h Fa <sub>max</sub> [N] <sup>3)</sup>									2500										
Running noise L <sub>PA</sub> [dB(A)] <sup>4)</sup>									75										
Efficiency at full load η [%]	94					92													
Min. operating temperature B <sub>Tempmin</sub> [°C] <sup>5)</sup>									-25										
Max. operating temperature B <sub>Tempmax</sub> [°C] <sup>5)</sup>									90										
Mounting orientation									Any										
Protection class									IP 54										
Weight m [Kg]	12.6					14.6													
Moment of inertia J <sub>1</sub> [Kgcm <sup>2</sup> ]	5.75	3.91	3.35	2.89	2.85	5.73	5.6	5.53	3.83	3.28	3.26	2.84							

<sup>1)</sup> The entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$ ; depending on the respective motor shaft diameter

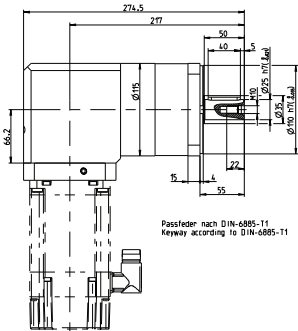
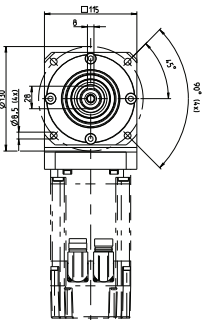
<sup>2)</sup> Approved for 1000x

<sup>3)</sup> With reference to the middle of the output shaft; the entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$

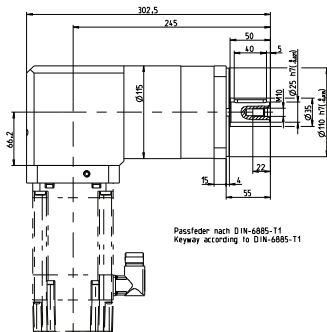
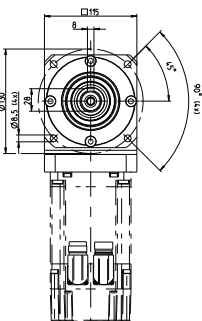
<sup>4)</sup> Noise level at a distance of 1 m; measured at a drive speed of  $n_1=3000\text{min}^{-1}$  without a load;  $i=5$

<sup>5)</sup> With reference to the middle of the housing surface

# 1 stage gearboxes

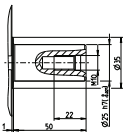


# 2 stage gearboxes



# Alternative output shaft options

Smooth shaft



# 8GA45-121

## Technical data



8GA45-121hh060k1mm

8GA45-121hh080k1mm

8GA45-121hh120k1mm

8GA45-121hh160k1mm

8GA45-121hh200k1mm

8GA45-121hh256k1mm

8GA45-121hh320k1mm

8GA45-121hh512k1mm

### Gearboxes

Number of stages	3							
Ratio i	60	80	120	160	200	256	320	512
Nominal output torque $T_{2N}$ [Nm] <sup>1)</sup>	260		230	260	230	260	230	120
Max. output torque $T_{2max}$ [Nm] <sup>1)</sup>	416		368	416	368	416	368	192
Emergency stop torque $T_{2estop}$ [Nm] <sup>2)</sup>	520		460	520	460	520	460	240
No load running torque at 20°C and 3,000 [min <sup>-1</sup> ] [Nm]	0.5							
Max. average input speed at 50% $T_{2N}$ and S1 $n_{1N50\%}$ [min <sup>-1</sup> ]	3500							
Max. average input speed at 100% $T_{2N}$ and S1 $n_{1N100\%}$ [min <sup>-1</sup> ]	3500							
Max. input speed $n_{1max}$ [min <sup>-1</sup> ]	6500							
Max. backlash $j_k$ [arcmin]	<18							
Reduced backlash $j_r$ [arcmin]	-							
Torsional rigidity $C_{t21}$ [Nm/arcmin]	12							
Tilting rigidity $C_{2K}$ [Nm/arcmin]	-							
Max. tilting moment $M_{2KMax}$ [Nm]	-							
Max. radial force for 30,000 h $F_{rmax}$ [N] <sup>3)</sup>	2400							
Max. radial force for 20,000 h $F_{rmax}$ [N] <sup>3)</sup>	2950							
Max. axial force for 30,000 h $F_{amax}$ [N] <sup>3)</sup>	2100							
Max. axial force for 20,000 h $F_{amax}$ [N] <sup>3)</sup>	2500							
Running noise $L_{PA}$ [dB(A)] <sup>4)</sup>	75							
Efficiency at full load $\eta$ [%]	88							
Min. operating temperature $B_{Tempmin}$ [°C] <sup>5)</sup>	-25							
Max. operating temperature $B_{Tempmax}$ [°C] <sup>5)</sup>	90							
Mounting orientation	Any							
Protection class	IP 54							
Weight m [Kg]	16.6							
Moment of inertia $J_1$ [Kgcmm <sup>2</sup> ]	5.62	3.28	5.47	2.84				

<sup>1)</sup> The entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$ ; depending on the respective motor shaft diameter

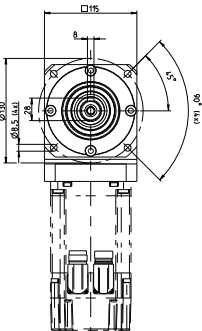
<sup>2)</sup> Approved for 1000x

<sup>3)</sup> With reference to the middle of the output shaft; the entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$

<sup>4)</sup> Noise level at a distance of 1 m; measured at a drive speed of  $n_1=3000\text{min}^{-1}$  without a load;  $i=5$

<sup>5)</sup> With reference to the middle of the housing surface

### 3 stage gearboxes



### Alternative output shaft options

Smooth shaft

