

# 8GP40-080

## Technical data



8GP40-080hh003klmm

8GP40-080hh004klmm

8GP40-080hh005klmm

8GP40-080hh008klmm

8GP40-080hh010klmm

8GP40-080hh009klmm

8GP40-080hh012klmm

8GP40-080hh015klmm

8GP40-080hh016klmm

8GP40-080hh020klmm

8GP40-080hh025klmm

8GP40-080hh032klmm

8GP40-080hh040klmm

8GP40-080hh064klmm

8GP40-080hh100klmm

### Gearboxes

Number of stages					1	2									
Ratio i	3	4	5	8	10	9	12	15	16	20	25	32	40	64	100
Nominal output torque T <sub>2N</sub> [Nm] <sup>1)</sup>	85	115	110	50	38	130	120	110	120		110	120	110	50	38
Max. output torque T <sub>2max</sub> [Nm] <sup>1)</sup>	136	184	176	80	61	208	192	176	192		176	192	176	80	61
Emergency stop torque T <sub>2estop</sub> [Nm] <sup>2)</sup>	170	230	220	100	76	260	240	220	240		220	240	220	100	76
No load running torque at 20°C and 3,000 [min <sup>-1</sup> ] [Nm]	0.3	0.2													
Max. average input speed at 50% T <sub>2N</sub> and S1 n <sub>1N50%</sub> [min <sup>-1</sup> ]	3900	3650	4000												
Max. average input speed at 100% T <sub>2N</sub> and S1 n <sub>1N100%</sub> [min <sup>-1</sup> ]	2400	2150	2650	4000		2700	3450	4000							
Max. input speed n <sub>1max</sub> [min <sup>-1</sup> ]	7000														
Max. backlash j <sub>lt</sub> [arcmin]	<8					<12									
Reduced backlash j <sub>lt</sub> [arcmin]						-									
Torsional rigidity C <sub>t21</sub> [Nm/arcmin]	6					6.5									
Tilting rigidity C <sub>2K</sub> [Nm/arcmin]						-									
Max. tilting moment M <sub>2KMax</sub> [Nm]						-									
Max. radial force for 30,000 h Fr <sub>max</sub> [N] <sup>3)</sup>						650									
Max. radial force for 20,000 h Fr <sub>max</sub> [N] <sup>3)</sup>						750									
Max. axial force for 30,000 h Fa <sub>max</sub> [N] <sup>3)</sup>						900									
Max. axial force for 20,000 h Fa <sub>max</sub> [N] <sup>3)</sup>						1000									
Running noise L <sub>PA</sub> [dB(A)] <sup>4)</sup>						60									
Efficiency at full load η [%]	96					94									
Min. operating temperature B <sub>Tempmin</sub> [°C] <sup>5)</sup>						-25									
Max. operating temperature B <sub>Tempmax</sub> [°C] <sup>5)</sup>						90									
Mounting orientation						Any									
Protection class						IP 54									
Weight m [Kg]	2.1					2.6									
Moment of inertia J <sub>1</sub> [Kgcm <sup>2</sup> ]	0.77	0.52	0.45	0.39		0.74	0.72	0.71	0.5	0.44	0.39				

<sup>1)</sup> The entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$ ; depending on the respective motor shaft diameter

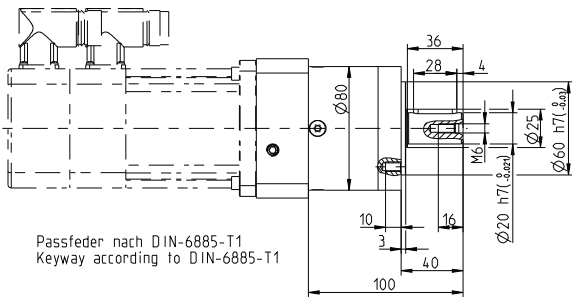
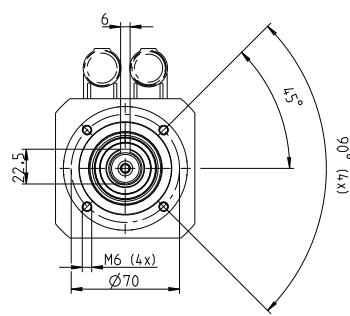
<sup>2)</sup> Approved for 1000x

<sup>3)</sup> With reference to the middle of the output shaft; the entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$

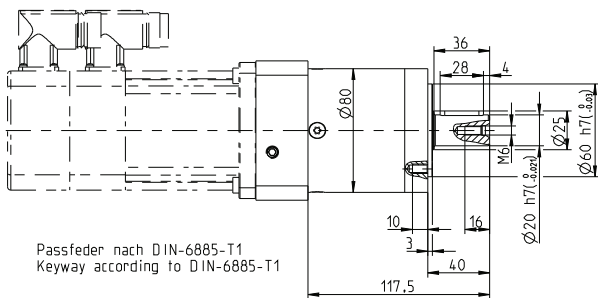
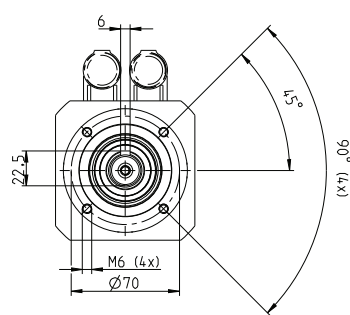
<sup>4)</sup> Noise level at a distance of 1 m; measured at a drive speed of  $n_1=3000\text{min}^{-1}$  without a load;  $i=5$

<sup>5)</sup> With reference to the middle of the housing surface

## 1 stage gearboxes

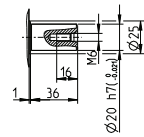


## 2 stage gearboxes



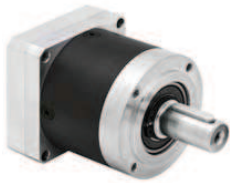
## Alternative output shaft options

Smooth shaft



# 8GP40-080

## Technical data



8GP40-080hh060k1mm

8GP40-080hh080k1mm

8GP40-080hh120k1mm

8GP40-080hh160k1mm

8GP40-080hh200k1mm

8GP40-080hh256k1mm

8GP40-080hh320k1mm

8GP40-080hh512k1mm

### Gearboxes

Number of stages	3							
Ratio i	60	80	120	160	200	256	320	512
Nominal output torque $T_{2N}$ [Nm] <sup>1)</sup>	110	120	110	120	110	120	110	50
Max. output torque $T_{2max}$ [Nm] <sup>1)</sup>	176	192	176	192	176	192	176	80
Emergency stop torque $T_{2estop}$ [Nm] <sup>2)</sup>	220	240	220	240	220	240	220	100
No load running torque at 20°C and 3,000 [min <sup>-1</sup> ] [Nm]	0.2							
Max. average input speed at 50% $T_{2N}$ and S1 $n_{1N50\%}$ [min <sup>-1</sup> ]	4000							
Max. average input speed at 100% $T_{2N}$ and S1 $n_{1N100\%}$ [min <sup>-1</sup> ]	4000							
Max. input speed $n_{1max}$ [min <sup>-1</sup> ]	7000							
Max. backlash $j_t$ [arcmin]	<14							
Reduced backlash $j_r$ [arcmin]	-							
Torsional rigidity $C_{t21}$ [Nm/arcmin]	6.3							
Tilting rigidity $C_{2K}$ [Nm/arcmin]	-							
Max. tilting moment $M_{2KMax}$ [Nm]	-							
Max. radial force for 30,000 h $F_{rmax}$ [N] <sup>3)</sup>	650							
Max. radial force for 20,000 h $F_{rmax}$ [N] <sup>3)</sup>	750							
Max. axial force for 30,000 h $F_{amax}$ [N] <sup>3)</sup>	900							
Max. axial force for 20,000 h $F_{amax}$ [N] <sup>3)</sup>	1000							
Running noise $L_{PA}$ [dB(A)] <sup>4)</sup>	60							
Efficiency at full load $\eta$ [%]	90							
Min. operating temperature $B_{Tempmin}$ [°C] <sup>5)</sup>	-25							
Max. operating temperature $B_{Tempmax}$ [°C] <sup>5)</sup>	90							
Mounting orientation	Any							
Protection class	IP 54							
Weight m [Kg]	3.1							
Moment of inertia $J_1$ [Kgcmm <sup>2</sup> ]	0.51	0.5	0.7	0.39				

<sup>1)</sup> The entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$ ; depending on the respective motor shaft diameter

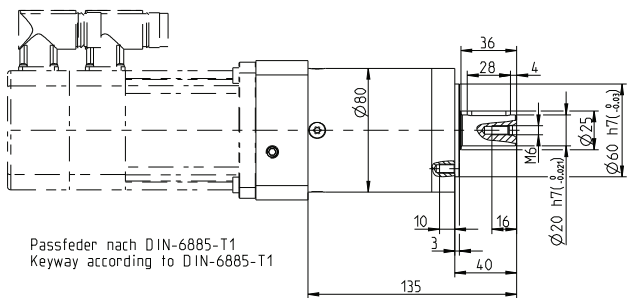
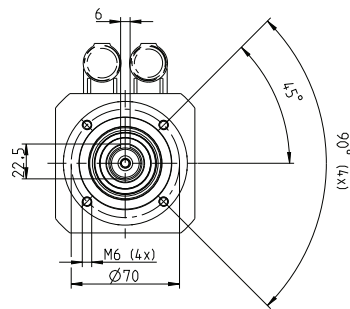
<sup>2)</sup> Approved for 1000x

<sup>3)</sup> With reference to the middle of the output shaft; the entries refer to an output shaft speed of  $n_2=100\text{min}^{-1}$  and application factor  $K_A=1$  as well as S1 operating mode for electrical machines and  $T=30^\circ\text{C}$

<sup>4)</sup> Noise level at a distance of 1 m; measured at a drive speed of  $n_1=3000\text{min}^{-1}$  without a load;  $i=5$

<sup>5)</sup> With reference to the middle of the housing surface

3 stage gearboxes



Alternative output shaft options

Smooth shaft

