# 8GP30-060

#### **Technical data**



8GP30-060hh005klmm

8GP30-060hh010klmm

8GP30-060hh025klmm

| Gearboxes  |       |       |      |
|--|-------|-------|------|
| Number of stages   | 1     |       | 2    |
| Ratio i  | 5     | 10    | 25   |
| Nominal output torque T <sub>2N</sub> [Nm] <sup>1)</sup>   | 30    | 15    | 30   |
| Max. output torque T <sub>2max</sub> [Nm] <sup>1)</sup>  | 48    | 24    | 48   |
| Emergency stop torque T <sub>2estop</sub> [Nm] <sup>2)</sup>                                     | 60    | 30    | 60   |
| No load running torque at 20°C and 3,000 [min <sup>-1</sup> ] [Nm]                               |       | 0.1   |      |
| Max. average input speed at 50% T <sub>2N</sub> and S1 n <sub>1N50%</sub> [min <sup>-1</sup> ]   |       | 4500  |      |
| Max. average input speed at 100% T <sub>2N</sub> and S1 n <sub>1N100%</sub> [min <sup>-1</sup> ] | 4500  |       |      |
| Max. input speed n <sub>1max</sub> [min <sup>-1</sup> ]  | 13000 |       |      |
| Max. backlash j <sub>t</sub> [arcmin]  | <12   |       | <15  |
| Reduced backlash j <sub>t</sub> [arcmin]   |       | -     |      |
| Torsional rigidity C <sub>t21</sub> [Nm/arcmin]  | 2.3   |       | 2.5  |
| Tilting rigidity C <sub>2K</sub> [Nm/arcmin]   |       | -     |      |
| Max. tilting moment M <sub>2KMax</sub> [Nm]  |       | -     |      |
| Max. radial force for 30,000 h Fr <sub>max</sub> [N] <sup>3)</sup>                               | 340   |       |      |
| Max. radial force for 20,000 h Fr <sub>max</sub> [N] <sup>3)</sup>                               | 400   |       |      |
| Max. axial force for 30,000 h Fa <sub>max</sub> [N] <sup>3)</sup>                                | 450   |       |      |
| Max. axial force for 20,000 h Fa <sub>max</sub> [N] <sup>3)</sup>                                | 500   |       |      |
| Running noise L <sub>PA</sub> [dB(A)] <sup>4)</sup>  | 58    |       |      |
| Efficiency at full load η [%]  | 96    |       | 94   |
| Min. operating temperature B <sub>Tempmin</sub> [°C] <sup>5)</sup>                               | -25   |       |      |
| Max. operating temperature B <sub>Tempmax</sub> [°C] <sup>5)</sup>                               | 90    |       |      |
| Mounting orientation   | Any   |       |      |
| Protection class   |       | IP 54 |      |
| Weight m [Kg]  | 0.9   |       | 1.1  |
| Moment of inertia J <sub>1</sub> [Kgcm <sup>2</sup> ]  | 0.2   | 0.18  | 0.19 |

<sup>1)</sup> The entries refer to an output shaft speed of  $n_2$ =100min<sup>-1</sup> and application factor  $K_A$ =1 as well as S1 operating mode for electrical machines and T=30°C; depending on the respective motor shaft diameter

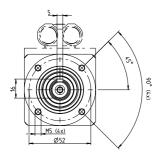
<sup>&</sup>lt;sup>2)</sup> Approved for 1000x

<sup>&</sup>lt;sup>3)</sup> With reference to the middle of the output shaft; the entries refer to an output shaft speed of n<sub>2</sub>=100min<sup>-1</sup> and application factor K<sub>A</sub>=1 as well as S1 operating mode for electrical machines and T=30°C

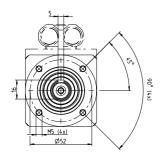
 $<sup>^{4)}</sup>$  Noise level at a distance of 1 m; measured at a drive speed of  $n_1$ =3000min $^{-1}$  without a load; i=5

 $<sup>^{\</sup>rm 5)}$  With reference to the middle of the housing surface

### 1 stage gearboxes



## 2 stage gearboxes



## Alternative output shaft options





