# 8GP30-040

#### **Technical data**



8GP30-040hh005klmm

8GP30-040hh010klmm

8GP30-040hh025klmm

| Gearboxes  |           |      |      |
|--|-----------|------|------|
| Number of stages   | 1         |      | 2    |
| Ratio i  | 5         | 10   | 25   |
| Nominal output torque T <sub>2N</sub> [Nm] <sup>1)</sup>   | 13        | 5    | 13   |
| Max. output torque T <sub>2max</sub> [Nm] <sup>1)</sup>  | 20.8      | 8    | 20.8 |
| Emergency stop torque T <sub>2estop</sub> [Nm] <sup>2)</sup>                                     | 26        | 10   | 26   |
| No load running torque at 20°C and 3,000 [min <sup>-1</sup> ] [Nm]                               | 0.1       |      | 0.05 |
| Max. average input speed at 50% T <sub>2N</sub> and S1 n <sub>1N50%</sub> [min <sup>-1</sup> ]   |           | 5000 |      |
| Max. average input speed at 100% T <sub>2N</sub> and S1 n <sub>1N100%</sub> [min <sup>-1</sup> ] | 5000      |      |      |
| Max. input speed n <sub>1max</sub> [min <sup>-1</sup> ]  | 18000     |      |      |
| Max. backlash j <sub>t</sub> [arcmin]  | <15       |      | <19  |
| Reduced backlash j <sub>t</sub> [arcmin]   |           | -    |      |
| Torsional rigidity C <sub>121</sub> [Nm/arcmin]  | 1         |      | 1.1  |
| Tilting rigidity C <sub>2K</sub> [Nm/arcmin]   |           | -    |      |
| Max. tilting moment M <sub>2KMax</sub> [Nm]  |           | -    |      |
| Max. radial force for 30,000 h Fr <sub>max</sub> [N] <sup>3)</sup>                               | 160       |      |      |
| Max. radial force for 20,000 h Fr <sub>max</sub> [N] <sup>3)</sup>                               | 200       |      |      |
| Max. axial force for 30,000 h Fa <sub>max</sub> [N] <sup>3)</sup>                                | 160       |      |      |
| Max. axial force for 20,000 h Fa <sub>max</sub> [N] <sup>3)</sup>                                | 200       |      |      |
| Running noise L <sub>PA</sub> [dB(A)] <sup>4)</sup>  |           | 58   |      |
| Efficiency at full load η [%]  |           | 96   | 94   |
| Min. operating temperature B <sub>Tempmin</sub> [°C] <sup>5)</sup>                               |           | -25  |      |
| Max. operating temperature B <sub>Tempmax</sub> [°C] <sup>5)</sup>                               |           | 90   |      |
| Mounting orientation   | Any       |      |      |
| Protection class   | IP 54     |      |      |
| Weight m [Kg]  | 0.35 0.45 |      |      |
| Moment of inertia J₁ [Kacm²]   | 0.03      |      |      |

 $<sup>^{1)}</sup>$  The entries refer to an output shaft speed of  $n_2$ =100min $^{-1}$  and application factor  $K_A$ =1 as well as S1 operating mode for electrical machines and T=30 $^{\circ}$ C; depending on the respective motor shaft diameter

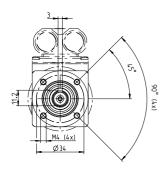
<sup>2)</sup> Approved for 1000x

<sup>3)</sup> With reference to the middle of the output shaft; the entries refer to an output shaft speed of n2=100min<sup>-1</sup> and application factor K<sub>A</sub>=1 as well as S1 operating mode for electrical machines and T=30°C

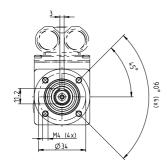
 $<sup>^{4)}</sup>$  Noise level at a distance of 1 m; measured at a drive speed of  $\rm n_1$ =3000min $^{-1}$  without a load; i=5

 $<sup>^{\</sup>rm 5)}$  With reference to the middle of the housing surface

### 1 stage gearboxes



## 2 stage gearboxes



## Alternative output shaft options





