

## 2.3 BC4321 and BC4321-1

### 2.3.1 General information

CAN (Controller Area Network) has spread considerably in automation technology. CAN topology is based on a line structure and uses twisted pair wires for data transfer. CANopen is a higher-layer protocol based on CAN. This standardized protocol offers highly flexible configuration possibilities.

The BC4321 and BC4321-1 bus controllers make it possible to connect X2X Link I/O nodes to CANopen. Both bus controllers have automatic transfer rate detection and AutoMapping of the I/O modules connected with X2X Link. All CANopen operating modes such as synchronous, event, and polling are supported together with PDO linking, life-/node guarding, emergency objects, and much more.

Unlike the BC4321, the BC4321-1 bus controller offers the possibility of supplying the CAN interface via the M12 CAN bus plug. This eliminates the need for a voltage feed via the M8 supply plug.

- Fieldbus: CANopen
- 8 digital channels, can be configured as input or output
- Simple I/O configuration via the fieldbus
- Integrated connection to the local expansions via X2X Link for 39 additional modules
- Configurable cycle time for local expansion from 400 µs to 1.3 ms (default: 1 ms)

### Information:

This bus controller only supports the default function model of multi-function modules. The default function model is explained in the description for each multi-function module.

### 2.3.2 Order data

Model number	Short description	Figure
	<b>CANopen bus controller</b>	
X67BC4321	X67 CAN bus controller, X2X Link supply 3 W, 8 digital channels can be configured as input or output, 24 VDC, 0.5 A, configurable input filter, LED status indicators	
X67BC4321-1	X67 CAN bus controller, X2X Link supply 3 W, 8 digital channels can be configured as input or output, 24 VDC, 0.5 A, configurable input filter, I/O supply possible via CAN plug, LED status indicators	
	<b>Required accessories</b>	
X67AC8C00	X67 CAN bus Y-connector	
X67AC9C03	X67 CAN bus terminating resistor M12	
See 2.3.18 "Required cables and connectors" on page 105		
		

Table 20: BC4321 / BC4321-1 - Order data

### 2.3.3 Technical data

Product ID	BC4321	BC4321-1
<b>Short description</b>		
Bus controller	CANopen	
Inputs/outputs	8 digital channels, configured as inputs or outputs using software, inputs with special functions	
Rated voltage	24 VDC	
<b>Fieldbus</b>		
Type	CANopen	
Design	M12 circular plugs (plug on the module)	
Maximum distance	1000 m	
Maximum transfer rate	1 MBit/s, automatic transfer rate detection	
<b>Digital inputs</b>		
Input filter		
Hardware	≤10 µs (channels 1 - 4) / ≤70 µs (channels 5 - 8)	
Software	Default 0 ms, can be configured between 0 and 25 ms in 0.2 ms intervals	
Input circuit	Sink	
Additional functions for inputs	50 kHz event counting, gate measurement	

Table 21: BC4321 / BC4321-1 - Technical data

Product ID	BC4321	BC4321-1
Digital outputs		
Rated output current	0.5 A	
Total current	4.0 A	
Output circuit	Source	
Output protection	Thermal cutoff for overcurrent and short circuit, integrated protection for switching inductances, reverse polarity protection for output supply	
General information		
Status indicators	I/O function for each channel, supply voltage, bus function	
Diagnostics		
I/O supply	Yes, with status LED and software status	
Outputs	Yes, with status LED and software status	
Electrical isolation		
Fieldbus - X2X Link	No	Yes
Channel - Bus	Yes (CAN and X2X)	No (CAN) / Yes (X2X)
Channel - Channel	No	No
Sensor/actuator supply	0.5 A total current	
Power consumption		
Fieldbus	2.7 W	3.8 W
I/O internal	2.0 W	-
X2X Link supply	6.6 W at maximum power output for connected I/O modules	5.5 W at maximum power output for connected I/O module
Power output	3.0 W X2X Link supply for I/O modules	3.0 W X2X Link supply for I/O modules
Connection type		
Fieldbus	M12 (A-coded)	
X2X Link	M12 (B-coded)	
Inputs/outputs	M8 (3-pin)	
Module supply	M8 (4-pin)	
Certification	CE, cRUus, GOST-R	
Ex zone 2	II 3G EEx nA II T5, IP67, Ta = 0 - 60°C	
Operational conditions		
Operating temperature	0 to +60°C	
Mounting orientation	Any	
Installation at altitudes above sea level		
0 - 2000 m	No derating	
>2000 m	Reduction of ambient temperature by 0.5°C per 100 m	
Protection type	IP67	
Storage and transport conditions		
Temperature	-25 to +85°C	
Mechanical characteristics		
Dimensions (W x H x D)	53 x 85 x 42 mm	
Weight	195 g	
Torque for connections		
M8	Max. 0.4 Nm	
M12	Max. 0.6 Nm	

Table 21: BC4321 / BC4321-1 - Technical data (Forts.)

### 2.3.4 Additional technical data

Product ID	BC4321	BC4321-1
<b>Module supply</b>		
Rated voltage	24 VDC	
Voltage range	18 - 30 VDC	
Integrated protection	Reverse polarity protection	
Power consumption Sensor/actuator supply	Max. 12 W <sup>1)</sup>	
<b>Sensor/actuator supply</b>		
Voltage	Module supply minus voltage drop for short circuit protection	
Voltage drop for short circuit protection at 500 mA	Max. 2 VDC	
Total current	Max. 0.5 A	
Short circuit protection	Yes	
<b>Fieldbus</b>		
Controller	SJA 1000 controller	
Processor	16-bit RISC processor	
Memory	128 KB	
Network-capable	Yes	
Bus termination resistor	Can be optionally screwed onto the Y-connector (see Accessories chapter in the section 4.3 "Connectors" on page 722)	
<b>Digital inputs</b>		
Input voltage	18 - 30 VDC	
Input current at 24 VDC	Typ. 4 mA	
Input resistance	Typ. 6 kΩ	
Switching threshold Low High	<5 VDC >15 VDC	
<b>Event counter</b>		
Number of counters	2	
Counter 1	Input 1	
Counter 2	Input 3	
Signal form	Square wave pulse	
Input frequency	Max. 50 kHz	
Counter frequency	Max. 50 kHz	
Counter size	16-bit	
Evaluation	Each negative edge, cyclic counter	

Table 22: BC4321 / BC4321-1 - Additional technical data

Product ID	BC4321	BC4321-1
Gate measurement		
Number of gate measurements	1	
Gate measurement using	Input 2 or Input 4	
Signal form	Square wave pulse	
Evaluation	Positive edge - Negative edge	
Pulse length	$\geq 20 \mu\text{s}$	
Length of pauses between pulses	$\geq 100 \mu\text{s}$	
Internal counter frequency	48 MHz, 3 MHz, 187.5 kHz	
Counter size	16-bit	
Digital outputs		
Design	FET positive switching	
Switching voltage	Module supply minus residual voltage	
Diagnostics status	Output monitoring with 10 ms delay	
Leakage current when switched off	$5 \mu\text{A}$	
Residual voltage	<0.3 V @ 0.5 A rated current	
Short circuit peak current	<12 A	
Switching on after overload cutoff	Approx. 10 ms (depends on the module temperature)	
Switching delay 0 → 1 1 → 0	$<400 \mu\text{s}$ $<400 \mu\text{s}$	
Switching frequency Resistive load Inductive load	Max. 100 Hz See the section 6.2.13 "Switching inductive loads" on page 260 (at 90% duty cycle)	
Braking voltage when switching off inductive loads	50 VDC	
General information		
Isolation voltage betw. channel and bus	500 V <sub>eff</sub>	
B&R ID code	\$17D4	\$A40E

Table 22: BC4321 / BC4321-1 - Additional technical data (Forts.)

- 1) The power consumption of the sensors and actuators connected to the module should not exceed 12 W.

### 2.3.5 Status LEDs

Figure	LED	Description		
 <p>Status indicator 1: left: green; right: red</p> <p>Status indicator 2: left: green; right: red</p>	Status indicator 1	LED	Status	Description
		Green	Off	No power supply
			Blinking (200 ms on / 200 ms off)	Preoperational mode
			On	RUN mode
			Blinking (200 ms on / 1 s off)	Stop mode
	Status indicator 2		Blinking (3 ms on / 500 ms off)	Flash delete in progress
		Red	Off	No supply or everything is OK
			Blinking (200 ms on / 1 s off)	Bus errors
			On	Bus errors: Bus is off
			Blinks 3 x and then is off for 1 s	Transfer rate selection
			Blinking (400 ms on / 800 ms off)	Invalid node switch position
			Green/red	Flickering
				Transfer rate detection in progress
	1 - 8	Input / output status of the corresponding channel. The LEDs are orange.		
	Status indicator 2	Status indicator for module function.		
		LED	Status	Description
		Green	Off	Module supply not connected
			Single flash	Reset mode
			Blinking	Preoperational mode
			On	RUN mode
		Red	Off	Module supply not connected or everything is OK
			On	Error or reset state
			Single flash	Warning / error for an I/O channel. Level monitoring for digital outputs has been triggered.
			Double flash	Supply voltage not in the valid range

Table 23: BC4321 / BC4321-1 - Status LEDs

### 2.3.6 Connection elements

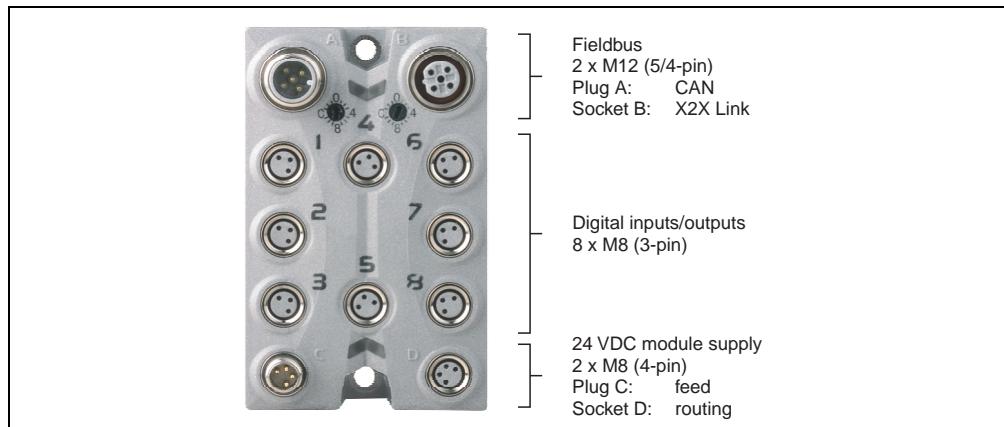


Figure 36: BC4321 / BC4321-1 - Connection elements

### 2.3.7 CAN interface

The BC4321 / BC4321-1 module is connected to the CAN fieldbus with pre-assembled cables. The connection is made using a circular plug (1 x M12, 5-pin).

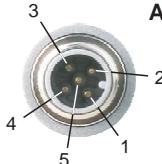
Connection	Pin assignments				
	Pin	CAN / BC4321		CAN / BC4321-1	
<b>A</b> 	1	SHLD	Shield	SHLD	Shield
	2	NC	-	+24 VDC	I/O supply
	3	CAN_L	CAN ground	CAN_L	CAN ground
	4	CAN_H	CAN high	CAN_H	CAN high
	5	CAN_L	CAN low	CAN_L	CAN low
	A ... A-coded plug in the module, input SHLD ... Shield connection made via threaded insert in the module				

Table 24: BC4321 / BC4321-1 - CAN interface

The bus controller is connected to a CAN fieldbus using a Y-connector. This allows the bus controller to be exchanged without breaking the fieldbus connection.

The bus termination resistance is housed in a plug and screwed onto the Y-connector as needed.

For information about accessories and connection examples, see:

- 2.3.18 "Required cables and connectors" on page 105 in this section
- 14 "Overview of pin connections" on page 647 in this section
- In the chapter 5 "Accessories" on page 651

### 2.3.8 X2X Link

The BC4321 / BC4321-1 module is connected to the X2X Link with pre-assembled cables. The connection is made using a circular plug (1 x M12, 4-pin).

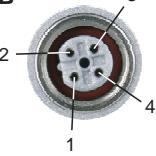
Connection	Pin assignments	
	Pin	Name
<b>B</b> 	1	X2X+
	2	X2X
	3	X2X <sub>⊥</sub>
	4	X2X <sub>  </sub>
B ... B-coded socket in the module, output		
SHLD ... Shield connection made via threaded insert in the module		

Table 25: BC4321 / BC4321-1 X2X Link

### 2.3.9 Digital inputs/outputs

The digital inputs/outputs are connected using circular plugs (8 x M8, 3-pin).

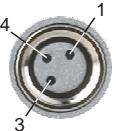
Connection	Pin assignments	
	Pin	Name
	1	24 VDC sensor/actuator supply <sup>1)</sup>
	3	GND
	4	Input / Output x
1) Sensors/actuators should not be supplied externally.		
	1	
	3	
	4	

Table 26: BC4321 / BC4321-1 - Digital inputs/outputs

### 2.3.10 24 VDC module supply

#### BC4321

The module supply connection is made using circular plugs (2 x M8, 4-pin). The supply feed is connected via plug C. Socket D is used for routing the supply to other modules (see also section 2.1.3 "Power supply" on page 88).

The maximum permitted current per supply is 4 A (sum 8 A).

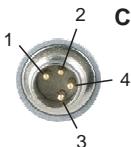
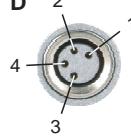
Connection	Pin assignments		
	Pin	Plug C	Socket D
	1	24 VDC fieldbus	24 VDC I/O
	2	24 VDC I/O	24 VDC I/O
	3	GND	GND
	4	GND	GND
C ... Plug on the module, supply feed D ... Socket on the module, supply routing			
			

Table 27: BC4321 - Module supply 24 VDC

**BC4321-1**

The module supply connection is made using circular plugs (2 x M8, 4-pin). The supply feed is connected via plug C. Socket D is used for routing the supply to other modules (see also section 2.1.3 "Power supply" on page 88). The X2X Link supply and the CAN and I/O supply are fed separately via pin 1 and 2

Connection	Pin assignments		
	Pin	Plug C	Socket D
 <b>C</b> <b>D</b>	1	24 VDC X2X Link	24 VDC I/O
	2	24 VDC CAN and I/O	24 VDC I/O
	3	GND	GND
	4	GND	GND
C ... Plug on the module, supply feed D ... Socket on the module, supply routing			

Table 28: BC4321-1 - 24 VDC module supply

The electrically isolated power supply integrated on the module for supplying the X2X Link can supply up to four X67 modules without having to install an additional PS1300 system supply module.

Because the supply for CAN bus and I/O is not isolated on this bus controller, it is not possible to shut off the I/O supply using an E-stop switch and still maintain CAN or X2X Link communication.

It is possible to supply the module with +24 VDC solely via the CAN circular plug A (pin 2).

### Information:

**There is no overload protection integrated here. An external 1.6 A fuse must therefore be installed to prevent damage to the module (e. g. caused by a short-circuit on the supply routing).**

The voltage transferred via pin 2 of the CAN plug is also available on pins 1 and 2 of the M8 circular socket D.

### Information:

**When transferring voltage via pin 2 of the CAN plugs and routing via socket D ...**

- ... a maximum of one additional I/O module can be connected.
- ... a maximum load of 400 mA can be applied to the digital I/Os.

### 2.3.11 Node numbers and transfer rate

Node numbers and transfer rates are configured using both bus controller number switches.

The transfer rate can be defined in two ways:

- Automatic detection by the bus controller (see section 2.3.12 "Automatic transfer rate detection" on page 101)
- Fixed setting by the user (see section 2.3.13 "Setting a fixed transfer rate" on page 102)

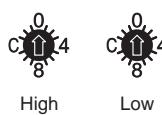


Figure 37: BC4321 / BC4321-1 - Number switches for node numbers and transfer rates

Switch position	Node number	Transfer rate
\$00	Not allowed	-
\$01 - \$7F	1 - 127	Automatically set by the bus controller (default) or fixed setting by the user.
\$80 - \$89	-	Setting a fixed transfer rate
\$8A - \$8F	Not allowed	-
\$90	Delete parameter See section 2.3.14 "Delete parameter" on page 103	-
\$91 - \$FF	Not allowed	-

Table 29: BC4321 / BC4321-1 - Node numbers and transfer rates

### 2.3.12 Automatic transfer rate detection

After booting, the bus controller BC4321/BC4321-1 goes into "ListenOnly" mode. That means the bus controller behaves passively on the bus and only listens.

The BC4321/BC4321-1 tries to receive valid objects. If errors occur during receiving, the controller switches to the next transfer rate from the search table.

If no objects are received, all transfer rates are tested cyclically. This procedure is repeated until valid objects are received.

#### Search table

The controller tests the transfer rate according to this table. Beginning with the starting transfer rate (1000 kBit/s), the controller switches to the next lower transfer rate. At the end of the table, the bus controller starts searching from the beginning again.

Transfer rate
1000 kBit/s
800 kBit/s
500 kBit/s
250 kBit/s
125 kBit/s
100 kBit/s
50 kBit/s
20 kBit/s
10 kBit/s

Table 30: BC4321 / BC4321-1 - Transfer rate search table

### 2.3.13 Setting a fixed transfer rate

The default setting for the bus controller is automatic transfer rate detection. It is also possible to set a fixed transfer rate using switch positions \$80 - \$89.

Switch position	Transfer rate
\$80	1000 kBit/s
\$81	800 kBit/s
\$82	500 kBit/s
\$83	250 kBit/s
\$84	125 kBit/s
\$85	100 kBit/s
\$86	50 kBit/s
\$87	20 kBit/s
\$88	10 kBit/s
\$89	Automatic transfer rate detection

Table 31: BC4321 / BC4321-1 - Possible fixed transfer rates

#### Programming a fixed transfer rate

- 1) Turn off power supply to the bus controller
- 2) Define transfer rate to be programmed by setting the node numbers (\$80 - \$89)
- 3) Turn power supply to the bus controller back on
- 4) Wait until the *status indicator 1* LED blinks with a red triple-flash (transfer rate is now programmed).
- 5) Turn off power supply to the bus controller
- 6) Set desired node number (\$01 - \$7F)
- 7) Turn power supply to the bus controller back on
- 8) Bus controller boots with the set node number and the programmed transfer rate

### 2.3.14 Delete parameter

Multiple parameters can be stored in the bus controller flash memory:

- Communication parameters
- Application parameters
- Fixed transfer rates

Deleting the parameters using the switch position \$90 returns the bus controller to its factory settings.

#### Deleting the parameters listed above

- 1) Turn off power supply to the bus controller
- 2) Set the node number to \$90
- 3) Turn power supply to the bus controller back on
- 4) Wait until the *status indicator 1* LED blinks green for 5 s (100 ms on / 200 ms off). The node number switch must be set to \$00 and then back to \$90 within this time window.
- 5) Wait until the *status indicator 1* LED blinks with a red double-flash (parameters are now deleted).
- 6) Turn off power supply to the bus controller
- 7) Set desired node number (\$01 - \$7F)
- 8) Turn power supply to the bus controller back on
- 9) Bus controller boots with the set node number and automatic transfer rate detection

### 2.3.15 Further documentation and import files (EDS)

Further documentation about CANopen bus controller functions, as well as the necessary import files for the master engineering tool, are available for download from the B&R Homepage ([www.br-automation.com](http://www.br-automation.com)).

### 2.3.16 Digital section

The CANopen bus controller is equipped with a digital mixed module. The technical data and its operation are similar to the DM1321 digital mixed module (see the section 6.2 "DM1321" on page 252).

### 2.3.17 System configuration

A digital mixed module is already integrated in the bus controller.

Module	Amount	Note
Digital and/or analog modules	40	40 physical modules are supported in total.

Table 32: BC4321 / BC4321-1 - System configuration, number of modules

## Information:

**3 W are provided by the bus controller for additional X67 modules or other modules that are based on X2X Link.**

**A PS1300 system supply module is required to achieve higher performance. This system supply module also provides 15 W for additional modules. It should be mounted in the middle of the modules that it will supply voltage to.**

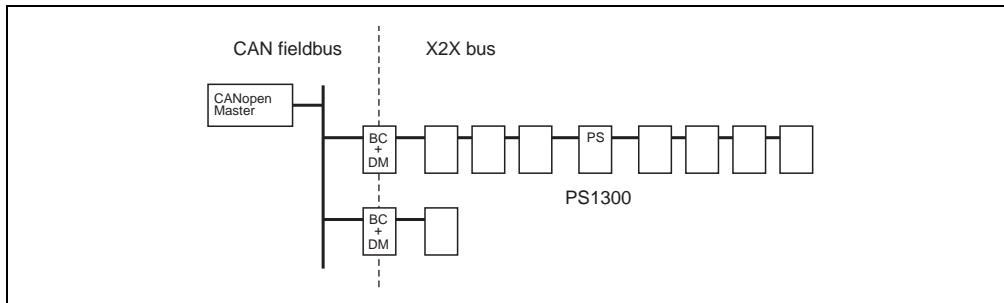


Figure 38: BC4321 / BC4321-1 - Integration in a CANopen network

### 2.3.18 Required cables and connectors

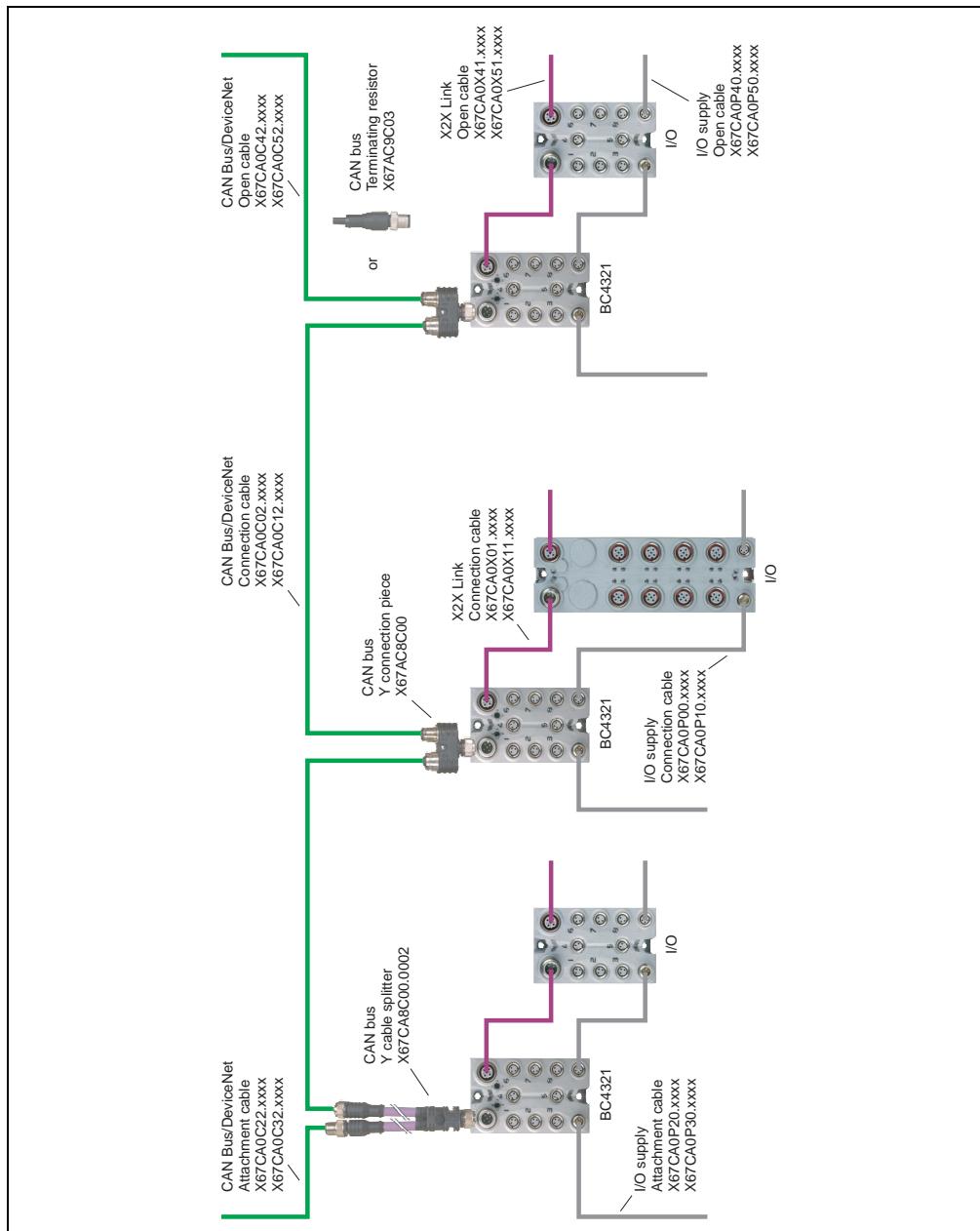


Figure 39: BC4321 / BC4321-1 - Required cables and connectors