8EAC0134.000-1

1 General information

I/O plug-in module 8EAC0134.000-1 can be used in the slot of an ACOPOS P3 8EI servo drive. The plug-in module provides 10 digital inputs/outputs, 3 analog inputs and 3 analog outputs.

Digital inputs/outputs 1 to 8 can be configured individually; digital inputs/outputs 9 and 10 can be configured in pairs as inputs or outputs.

Up to 4 high-speed (push-pull) outputs with maximum current of 100 mA, 4 standard (high-side) outputs with maximum current of 400 mA and 2 slow (high-side) outputs with maximum current of 2 A are available.

The digital inputs/outputs are also equipped with an internal reverse current protection circuit:

Even if the input voltage on one of the digital I/O connections exceeds the value of the supply voltage on connections X41E/29 and X41E/30, they are protected against damage by the internal reverse current protection circuit.

Information:

The type of individual digital I/O connections is not predefined at the factory. Before commissioning, configure the desired type (input or output) for each I/O connection in Automation Studio!

The analog inputs (±10 V differential inputs) are equipped with a configurable high-performance filter.¹⁾

The analog outputs can be used as either current or voltage outputs.

Information:

The type of individual analog outputs connections is not predefined at the factory. Before commissioning, configure the desired type (current or voltage output) for each analog output in Automation Studio!

2 Order data

| Order number | Short description | Figure | | |
|-----------------|---|------------|--|--|
| | Plug-in modules | | | |
| 8EAC0134.000-1 | ACOPOS P3 plug-in module, 8 digital I/O 24 V (4x 400 mA, 4x 100 mA) individually configurable as inputs or outputs, 2 digital I/O 24 V 2 A configurable in pairs as inputs or outputs, 3 analog differential inputs, 14-bit, 3 analog outputs, 12-bit, individually configurable as current or voltages outputs, order terminal block 8TB0230.221A-00 separately! | Ø) DIO/AIO | | |
| | Required accessories | 7 | | |
| | Terminals | 000 | | |
| 8TB0230.221A-00 | 30-pin push-in terminal block, 2-row, pitch: 2.54 mm, label 1: Numbered consecutively | XAE XAE | | |

Table 1: 8EAC0134.000-1 - Order data

3 Technical data

| Order number | 8EAC0134.000-1 | | |
|---------------------|--------------------------|--|--|
| General information | | | |
| Module type | ACOPOS P3 plug-in module | | |
| B&R ID code | 0xF038 | | |
| Slot | Slot 1 | | |
| Power consumption | Typ. 3 W | | |

Table 2: 8EAC0134.000-1 - Technical data

¹⁾ Combination of slew rate and linear-phase low-pass filter. Configuration takes place in Automation Studio.

| Order number | 8EAC0134.000-1 |
|---|--|
| Certifications | 0EAOV13%,000°1 |
| CE | Yes |
| UKCA | Yes |
| UL | cULus E225616 |
| OL | Power conversion equipment |
| KC | Yes |
| Inputs/Outputs | 163 |
| Module-side connection | 30-pin multipoint connector |
| Status indicators | None |
| Configuration of digital inputs/outputs | Input/Output 1 - 8: Individually configurable as inputs or outputs |
| Configuration of digital inputs/outputs | Input/Output 9 - 10: Configurable in pairs as inputs or outputs |
| Configuration of analog outputs | Individually configurable as current or voltage outputs |
| Incremental encoders 1) | marriadally cornigarable as current of voltage outputs |
| Counter size | 16-bit |
| Input frequency | |
| Evaluation | 4x |
| Signal form | Rectangle |
| 5 | Yes |
| Encoder monitoring | |
| Counter frequency | Max. 500 kHz |
| Reference frequency | Max. 125 kHz |
| Distance between edges | Min. 0.64 μs |
| Inputs | |
| Input 1 | Channel A |
| Input 2 | Channel B |
| Input 3 | Reference pulse R |
| Power supply 2) | |
| Reverse polarity protection | Yes |
| Power supply | |
| Minimum | 18 VDC |
| Nominal | 24 VDC |
| Maximum | 30 VDC |
| Digital inputs 3) | |
| Quantity | Max. 10 |
| Input current at 24 VDC | Inputs 1 - 8: Typ. 2.5 mA |
| | Inputs 9 - 10: Typ. 3 mA |
| Input filter | |
| Hardware | Inputs 1 - 8: No filter |
| | Inputs 9 - 10: Yes |
| Software | 5.12 µs (default) |
| | Between 0 and 20.97 ms |
| Connection type | 1-wire connections |
| Circuit | Sink |
| Input frequency 4) | Inputs 1 - 8: Max. 125 kHz |
| | Inputs 9 - 10: Max. 10 kHz |
| Switching threshold | .=. |
| Low | ≤5 V |
| High | ≥15 V |
| Input voltage | |
| Maximum | Supply voltage |
| Electrical isolation | |
| Channel - ACOPOS | Yes |
| Channel - Channel | No |
| Switching delay 5) | |
| Digital input | Inputs 1 - 8: Approx. 1 µs |
| | Inputs 9 - 10: Typ. 34 μs |
| Event counters 1) | |
| Signal form | Square wave pulse |
| Input frequency | Max. 125 kHz |
| Counter size | 16-bit |
| Inputs | |
| Input 1 | Counter 1 |
| Input 2 | Counter 2 |
| Trigger inputs 6 | |
| Quantity | 4 |
| Channels | Digital I/O 5 - 8 |
| Analog inputs 7) | |
| Quantity | 3 |
| Converter resolution | 14-bit ⁸⁾ |
| Open-circuit detection | Yes |
| Variant | Differential input |
| Electrical isolation | <u> </u> |
| Input - ACOPOS | Yes |
| Input - Input | No |
| paspas | |

Table 2: 8EAC0134.000-1 - Technical data

| Order number | 8EAC0134.000-1 | | | |
|--|--|--|--|--|
| | 8EAC0134.000-1 | | | |
| Input signal | 40 to 140 V | | | |
| Nominal | -10 to +10 V | | | |
| Data output | Synchronous to 400 µs cycle of the servo drive | | | |
| Input filter | Hardware: Third-order low-pass filter | | | |
| | Software: Configurable high-performance filter 9) | | | |
| Max. gain drift | ±800 μV/°C | | | |
| Max. offset drift | ±300 μV/°C | | | |
| Additional EMI noise 10) | ±0.5% ¹¹⁾ | | | |
| Common-mode range 12) | -12 to +12 V | | | |
| Common-mode rejection | Up to 1 kHz: 80 dB | | | |
| | Starting at 1 kHz: -20 dB/dec | | | |
| Basic accuracy 13) | ±0.05% ¹⁴⁾ | | | |
| Digital outputs | | | | |
| Quantity | Max. 10 | | | |
| Variant | Output 1 - 4: Push-pull transistor outputs | | | |
| | Output 5 - 8: High-side transistor outputs | | | |
| | Output 9 - 10: High-side transistor outputs | | | |
| Connection type | 1-wire connections | | | |
| Readable outputs | Yes | | | |
| Continuous current | Outputs 1 - 4: Max. 100 mA | | | |
| | Outputs 5 - 8: Max. 400 mA | | | |
| | Outputs 9 - 10: Max. 2 A | | | |
| Peak short-circuit current | Outputs 1 - 8: Approx. 10 A, 0.5 µs | | | |
| | Outputs 9 -10: Max. 90 A, 800 µs | | | |
| Switching frequency (resistive load) 15) | Outputs 1 - 4: Max. 125 kHz | | | |
| containing inequality (i.esistate ieau) | Outputs 5 - 8: Max. 10 kHz | | | |
| | Outputs 9 - 10: Max. 100 Hz | | | |
| Switching delay 16) | Outputs 1 - 8: <3 µs | | | |
| omening acidy | Outputs 9 - 10: 50 to 150 μs | | | |
| Electrical isolation | ' | | | |
| Output - ACOPOS | Yes | | | |
| Output - Output | No No | | | |
| | INU | | | |
| Switching voltage | | | | |
| Nominal | ≤Supply voltage | | | |
| Protection | | | | |
| Short-circuit proof | Yes | | | |
| Overload-proof | Yes | | | |
| Encoder emulation 1) | | | | |
| Switching frequency | Max. 125 kHz | | | |
| Outputs | | | | |
| Output 1 | Channel A | | | |
| Output 2 | Channel B | | | |
| Output 3 | Reference pulse R | | | |
| Analog outputs 17) | Treference pulse in | | | |
| Quantity | 3 | | | |
| , | - | | | |
| Variant | ±10 V or 0 to 20 mA (switchable) | | | |
| Converter resolution | 12-bit ¹⁸⁾ | | | |
| Settling time on output change 19) | Voltage output 0 - 10 V: Max. 200 μs | | | |
| | Current output 0 - 20 mA: Max. 300 µs | | | |
| Output protection | Voltage output: Short-circuit proof typ. 30 mA | | | |
| Load per channel | Voltage output: Load ≥ 1 kΩ | | | |
| | Current output: Load ≤ 600 Ω | | | |
| Max. gain drift | Voltage output: ±66 μV/°C | | | |
| | Current output: ±360 nA/°C | | | |
| Max. offset drift | Voltage output: ±110 μV/°C | | | |
| | Current output: ±480 nA/°C (offset at 0 LSB: typ. 10 μA) | | | |
| Basic accuracy 13) | | | | |
| Voltage | ±0.1% ¹⁴⁾ | | | |
| Current | ±0.1% ¹⁴⁾ | | | |
| Electrical isolation | =0.1.70 | | | |
| Output - ACOPOS | Yes | | | |
| • | | | | |
| Output - Output | No No | | | |
| Support | | | | |
| Motion system | | | | |
| mapp Motion | 5.08.2 and higher | | | |
| ACP10/ARNC0 | 5.08.2 and higher | | | |
| Ambient conditions | | | | |
| Temperature | | | | |
| Operation | | | | |
| Operation | 5 to 40°C | | | |
| Nominal | | | | |
| Nominal | 5 to 40°C | | | |
| Maximum | 55°C | | | |
| | | | | |

Table 2: 8EAC0134.000-1 - Technical data

8EAC0134.000-1

| Order number | 8EAC0134.000-1 |
|-----------------------|------------------|
| Relative humidity | |
| Operation | 5 to 85% |
| Storage | 5 to 95% |
| Transport | Max. 95% at 40°C |
| Mechanical properties | |
| Dimensions | |
| Width | 82 mm |
| Height | 24 mm |
| Depth | 103 mm |
| Weight | 79 g |

Table 2: 8EAC0134.000-1 - Technical data

- 1) Carry out wiring with shielded lines!
- 2) Carry out wiring for line lengths > 3 m with shielded lines!
- 3) When controlled by a push output or normally closed contact, the filter time should be increased to 655 µs in order to avoid disturbances from electromagnetic interference (EMI).
- 4) The maximum input frequency depends on the selected software function.
- 5) When controlled by a push output or normally closed contact, the switch-off time is extended depending on the length of the power supply cable since the line capacity is only discharged by the input current.
- 6) For additional technical data, see section "Digital inputs".
- 7) Carry out wiring with shielded lines! The measured value may temporarily deviate with cable lengths > 30 m when affected by electromagnetic interference (FMI)
- 8) The smallest measurable voltage change (voltage quantization) is typically 1.526 mV.
- 9) Combination of slew rate and linear-phase low-pass filter. Configuration takes place in Automation Studio.
- 10) During operation without high-performance filter.
- 11) Based on measured value 10 V.
- 12) Voltage of terminals + and against GND
- 13) 25°C at the factory.
- 14) Based on the current measured value.
- 15) Outputs 1 to 8: The maximum switching frequency depends on the selected software function.
- 16) Without and with resistive load at continuous current.
- 17) Carry out wiring with shielded lines! The signal may temporarily deviate with cable lengths > 30 m when affected by electromagnetic interference (EMI).
- 18) The smallest configurable voltage change (voltage quantization) is typically 5.371 mV. The smallest configurable current change (current quantization) is typically 5.86 μ A.
- 19) With resistive load.

4 Pinout

| Figure | X41E | Pin | Description | | Function | | |
|--|---|-----|----------------|-----------------------------------|---|---------------|---------|
| | | | | | Incremental encoders / Encoder emulation | Event counter | Trigger |
| | | 1 | Analog I 1 - | Analog input 1 minus | | | |
| | | 2 | Analog O 1 | Analog output 1 | | | |
| | | 3 | Analog I 1 + | Analog input 1 plus | | | |
| | | 4 | GND | GND | | | |
| | | 5 | Shield | Shield | | | |
| | | 6 | Shield | Shield | | | |
| | | 7 | Analog I 2 - | Analog input 2 minus | | | |
| | | 8 | Analog O 2 | Analog output 2 | | | |
| | | 9 | Analog I 2 + | Analog input 2 plus | | | |
| | | 10 | GND | GND | | | |
| | | 11 | Shield | Shield | | | |
| | +Vin 29 30 GND Digital I/O 9 27 28 Digital I/O 10 | 12 | Shield | Shield | | | |
| DIO/AIO | Digital I/O 7 25 (2) (2) 26 Digital I/O 8 | 13 | Analog I 3 - | Analog input 3 minus | | | |
| | Digital I/O 5 23 24 Digital I/O 6 | 14 | Analog O 3 | Analog output 3 | | | |
| F | Digital I/O 3 21 22 Digital I/O 4 Digital I/O 1 19 20 Digital I/O 2 | 15 | Analog I 3 + | Analog input 3 plus | | | |
| 1-00 | r 17 (□□O O□□ 18 n | 16 | GND | GND | | | |
| 7.00 | Analog I 3 1 15 1 16 Analog O 3 | 17 | Shield | Shield | | | |
| X41E | | 18 | Shield | Shield | | | |
| X41E | Analog I 2 { 11 | 19 | Digital I/O 1 | Digital input/output 1 | Channel A | Counter 1 | |
| | | 20 | Digital I/O 2 | Digital input/output 2 | Channel B | Counter 2 | |
| | | 21 | Digital I/O 3 | Digital input/output 3 | Reference pulse R | | |
| | | 22 | Digital I/O 4 | Digital input/output 4 | | | |
| | | 23 | Digital I/O 5 | Digital input/output 5 | | | Trigger |
| | | 24 | Digital I/O 6 | Digital input/output 6 | | | Trigger |
| | | 25 | Digital I/O 7 | Digital input/output 7 | | | Trigger |
| | | 26 | Digital I/O 8 | Digital input/output 8 | | | Trigger |
| | | 27 | Digital I/O 9 | Digital input/output 9 | | | |
| | | 28 | Digital I/O 10 | Digital input/output 10 | | | |
| | | 29 | +Vin | External power supply +18 +30 VDC | | | |
| | | 30 | GND | External power supply 0 V | | | |
| Terminal cross sec | ction | | | [mm²] | [AV | VG] | |
| Solid core / Multiple | -conductor lines | | | 0.14 - 0.5 | 26 - | - 20 | |
| Flexible, multiple wing Without wire end sleev | eeves | | | 0.14 - 0.5 0.14 - 0.25 | | - 20 - 24 | |
| Approbation data UL/C-UL-US CSA | | | | | | - 20 | - |

Table 3: DIO/AIO interface 8EAC0134.000-1 - Pinout

Information:

The digital and analog inputs/outputs can only be used if voltage is supplied to the module via connectors X41E/29 and X41E/30.

Notice!

Reverse current protection for the digital inputs is only ensured if the module is supplied with voltage via connections X41E/29 and X41E/30.

Danger!

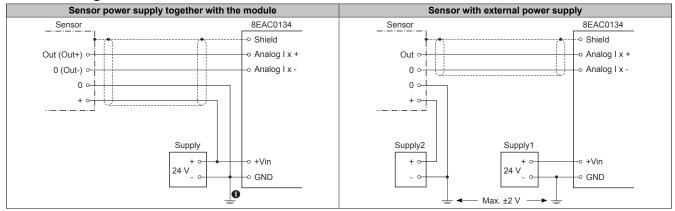
The digital inputs are isolated circuits. Therefore, only devices or components that have at least safe isolation per IEC 60364-4-41 or EN 61800-5-1 are permitted to be connected to these connections.

4.1 Wiring the analog inputs

The analog inputs are designed as balanced differential inputs. Both the + and - connections are high-impedance. This ensures that practically no input currents flow and thus no voltage drops occur on the signal lines. When connecting sensors without ground reference, however, it is important to ensure that their electric potential does not drift due to external couplings and the permissible common-mode voltage of the analog inputs is subsequently exceeded!

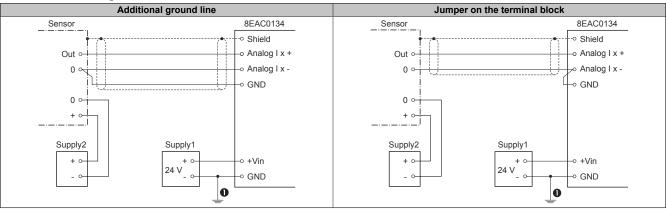
4.1.1 Connection examples

Sensors with ground reference



1) Grounding recommended

Sensors without ground reference



Grounding recommended

5 Input/Output circuit diagram

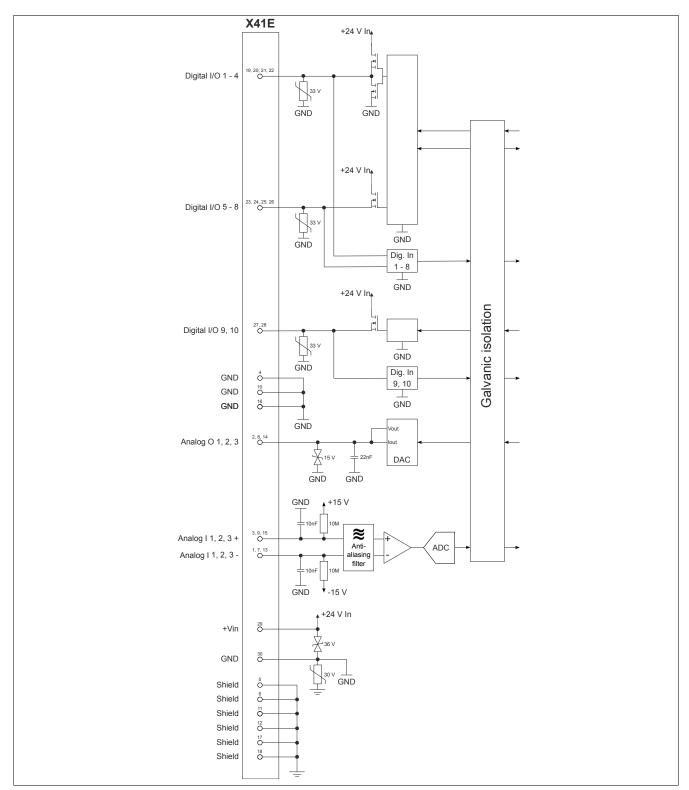


Figure 1: DIO/AIO interface 8EAC0134.000-1 - Input/Output circuit diagram